LS- Sasakian Manifold with Semi-symmetric Non-metric

F-connection

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Abstract— Hayden [1] introduced the idea of metric connection with torsion tensor in a Riemannian manifold. In 1975, Golab [2] studied quarter-symmetric connection in a differentiable manifold. T.Imai [3] discussed on hypersurfaces of a Riemannian manifold with semi-symmetric metric connection. In 1980, R. S. Mishra and S. N. Pandey [4] discussed on quarter-symmetric metric F-connection and in 1970, K. Yano [9] studied on semi-symmetric metric connections and their curvature tensors. In 1992, Nirmala S. Agashe and Mangala R. Chafle [5] studied semi-symmetric non-metric connection in a Riemannian manifold. Symmetric connections are also studied by K. Yano and T. Imai [10], A.Sharfuddin and S.I.Husain [8], R. N. Singh and S. K. Pandey [7] and many others. The purpose of this paper is to introduce a semi-symmetric non-metric F-connection in Lorentzian Special Sasakian manifold.

Keywords- Lorentzian Special Sasakian manifold, semi-symmetric non-metric F-connection, Nijenhuis tensor.

1. INTRODUCTION

An n-dimensional differentiable manifold M_n , on which there are defined a tensor field F of type (1, 1), a vector field T, a 1-form A and a Lorentzian metric g, satisfying for arbitrary vector fields X, Y, Z, ...

- (1.1) $\overline{\overline{X}} = -X A(X)T,$
- (1.2) A(T) = -1,

(1.3)
$$g(\overline{X},\overline{Y}) = g(X,Y) + A(X)A(Y)$$
, where $A(X) = g(X,T)$, $\overline{X} \stackrel{\text{def}}{=} FX$,

(1.4) (a) $(D_X F)(Y) + A(Y)\overline{X} - F(X,Y)T = 0 \Leftrightarrow$

(b)
$$(D_X F)(Y,Z) - A(Y) F(Z,X) - A(Z) F(X,Y) = 0$$
, where $F(X,Y) \stackrel{\text{def}}{=} g(\overline{X}, Y)$

(1.5) $D_X T = \overline{\overline{X}},$

Then M_n is called a Lorentzian special Sasakian manifold (an LS-Sasakian manifold).

In an LS-Sasakian manifold, it can be easily seen that

 $(1.6) \quad A(\overline{X}) = 0,$

- (1.7) rank F = n 1.
- $(1.8)^{`}F(X,Y) = -^{`}F(Y,X),$

(1.9) (a) $(D_X A)(\overline{Y}) = F(X, Y) \Leftrightarrow$ (b) $(D_X A)(Y) = -g(\overline{X}, \overline{Y})$

Nijenhuis tensor in an L-Contact manifold [6] is given by

(1.10)
$$N(X, Y, Z) = (D_{\overline{X}}F)(Y, Z) + (D_{\overline{Y}}F)(Z, X) + (D_{X}F)(Y, \overline{Z}) + (D_{Y}F)(\overline{Z}, X)$$

Where

 $N(X, Y, Z) \stackrel{\text{def}}{=} g(N(X, Y), Z)$

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2. SEMI-SYMMETRIC NON-METRIC F-CONNECTION IN AN LS-SASAKIAN MANIFOLD

An affine connection B is called non-metric connection, if

$$(2.1) \ B_X g \neq 0$$

An affine connection B is called F- connection, if

$$(2.2) \quad B_X F = 0$$

Let us consider non-metric F-connection having torsion tensor S of the form

(2.3) S(X,Y) = A(Y)X - A(X)Y,

Where S is the torsion tensor of the connection B.

Therefore,

Definition 2.1 A linear connection satisfying (2.1), (2.2) and (2.3) is called a semi-symmetric non-metric

F-connection.

Theorem 2.1 In an LS-Sasakian manifold, the connection *B* defined by

$$(2.4) B_X Y = D_X Y - A(Y)X + g(X, Y)T - 2A(X)Y$$

is a semi-symmetric non-metric connection, whose metric is given by

$$(2.5) (B_X g)(Y, Z) = 4A(X)g(Y, Z)$$

Proof. Put

$$(2.6) B_X Y = D_X Y + H(X, Y)$$

Where H is a tensor field of type (1, 2), given by

(2.7) $H(X,Y) = \alpha A(Y)X + \beta g(X,Y)T - 2A(X)Y,$

Where α and β are constants to be determined.

From (2.6) and (2.7), we get

(2.8)
$$B_X Y = D_X Y + \alpha A(Y) X + \beta g(X,Y) T - 2A(X) Y$$

Then, torsion tensor of the connection B is given by

(2.9)
$$S(X,Y) = H(X,Y) - H(Y,X)$$

Therefore

(2.10)
$$H(X,Y,Z) = \alpha A(Y)g(X,Z) + \beta A(Z)g(X,Y) - 2A(X)g(Y,Z)$$
 and

(2.11)
$$S(X,Y,Z) = H(X,Y,Z) - H(Y,X,Z)$$

Where

 $(2.12) \quad `H(X,Y,Z) \stackrel{\text{\tiny def}}{=} g(H(X,Y),Z)$

(2.13) $S(X,Y,Z) \stackrel{\text{\tiny def}}{=} g(S(X,Y),Z)$

From (2.2) and (2.8), we get

(2.14) $(D_X F)(Y) - \alpha A(Y) \overline{X} - \beta^{*} F(X, Y) T = 0$ 37

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In an LS-Sasakian manifold, we have

(2.15) $(D_X F)(Y) + A(Y)\overline{X} - F(X,Y)T = 0$

From (2.14) and (2.15), we get, $\alpha = -1$, $\beta = 1$

Putting these values in (2.8), we obtain (2.4).

Also

(2.16) $X(g(Y,Z)) = (B_Xg)(Y,Z) + g(B_XY,Z) + g(Y, B_XZ) = g(D_XY,Z) + g(Y, D_XZ)$

Using (2.4) in (2.16), we get (2.5).

Theorem 2.2 In an LS-Sasakian manifold with semi-symmetric non-metric F-connection B, we have

(2.17) (a)
$$B_X T = 2X + 2\overline{X}$$

(b)
$$(B_X A)(Y) = (D_X A)(Y) + g(X, Y) + 3A(X)A(Y)$$

(c)
$$(B_X F)(Y,Z) = (D_X F)(Y,Z) + 4A(X)F(Y,Z) - A(Y)F(Z,X) - A(Z)F(X,Y)$$

(d)
$$(B_X F)\left(\overline{Y}, \overline{Z}\right) - (B_X F)\left(\overline{\overline{Y}}, \overline{Z}\right) = 8A(X)g(\overline{Y}, \overline{Z})$$

(e)
$$(B_X F)\left(\overline{\overline{Y}}, \overline{\overline{Z}}\right) + (B_X F)\left(\overline{Y}, \overline{Z}\right) = 8A(X)F(Y,Z)$$

Theorem 2.3 Nijenhuis tensor with semi-symmetric non-metric F-connection B is given by

4A(X)g(Y,Z) + 4A(Y)g(Z,X)

Proof. (2.18) follows from (1.10) and (2.17) (c).

Theorem 2.4 The connection induced on a submanifold of an LS- Sasakian manifold with a Semi-symmetric non-metric F-connection with respect to unit normal vectors M and N is also Semi- symmetric non-metric F-connection iff

(2.19) (a)
$$h(\hat{X}, \hat{Y}) = p(\hat{X}, \hat{Y}) + \rho \tilde{g}(\hat{X}, \hat{Y})$$

(b)
$$k(\hat{X}, \hat{Y}) = q(\hat{X}, \hat{Y}) + \sigma \tilde{g}(\hat{X}, \hat{Y})$$

Proof. Let M_{2m-1} be submanifold of M_{2m+1} and let $c: M_{2m-1} \rightarrow M_{2m+1}$ be the inclusion map such that

$$d \in M_{2m-1} \to cd \in M_{2m+1} ,$$

Where *c* induces a Jacobian map (linear transformation) $J: T'_{2m-1} \rightarrow T'_{2m+1}$.

 T'_{2m-1} is tangent space to M_{2m-1} at point d and T'_{2m+1} is tangent space to M_{2m+1} at point cd such that

$$\hat{X}$$
 in M_{2m-1} at $d \to J\hat{X}$ in M_{2m+1} at cd

Let \tilde{g} be the induced metric tensor in M_{2m-1} , then

(2.20)
$$\tilde{g}(\hat{X}, \hat{Y}) = ((g(J\hat{X}, J\hat{Y}))b)$$

Semi- symmetric non-metric F-connection B in an LS- Sasakian manifold M_n is given by

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(2.21)
$$B_X Y = D_X Y - A(Y)X + g(X,Y)T - 2A(X)Y$$

Where X and Y are arbitrary vector fields of M_{2m+1} . Let

$$(2.22) \quad T = Jt - \rho M - \sigma N,$$

Where t is C^{∞} vector fields in M_{2m-1} . M, N are unit normal vectors to M_{2m-1} .

Denoting by \hat{D} the connection induced on the submanifold from *D*.

Put

$$(2.23) \qquad D_{JX}J\hat{Y} = J(\hat{D}_X\hat{Y}) - p(\hat{X},\hat{Y})M - q(\hat{X},\hat{Y})N$$

Where p and q are symmetric bilinear functions in M_{2m-1} . Also

$$(2.24) \qquad B_{JX}J\hat{Y}=J(\hat{B}_X\hat{Y})-h(\hat{X},\hat{Y})M-k(\hat{X},\hat{Y})N\;,$$

Where \dot{B} is the connection induced on the submanifold from B and h, k are symmetric bilinear functions in M_{2m-1} .

Inconsequence of (2.21), we have

$$(2.25) \qquad B_{JX}J\hat{Y} = D_{JX}J\hat{Y} - A(J\hat{Y})J\hat{X} + g(J\hat{X},J\hat{Y})T - 2A(J\hat{X})J\hat{Y}$$

Using (2.23), (2.24) and (2.25), we have

$$(2.26) \quad J(\hat{B}_{X}\hat{Y}) - h(\hat{X},\hat{Y})M - k(\hat{X},\hat{Y})N = J(\hat{D}_{X}\hat{Y}) - p(\hat{X},\hat{Y})M - q(\hat{X},\hat{Y})N - A(J\hat{Y})J\hat{X} + g(J\hat{X},J\hat{Y})T - 2A(J\hat{X})J\hat{Y}$$

Using (2.22), we get

$$(2.27) \qquad J(\dot{B}_X\hat{Y}) - h(\hat{X},\hat{Y})M - k(\hat{X},\hat{Y})N = J(\dot{D}_X\hat{Y}) - p(\hat{X},\hat{Y})M - q(\hat{X},\hat{Y})N - a(\hat{Y})J\hat{X} +$$

$$(Jt - \rho M - \sigma N)\tilde{g}(\hat{X}, \hat{Y}) - 2a(\hat{X})J\hat{Y}$$

Where $\tilde{g}(\hat{Y}, t) \stackrel{\text{\tiny def}}{=} a(\hat{Y})$

Using (2.19) (a) and (2.19) (b), we get

$$(2.28) \qquad \dot{B}_X \hat{Y} = \dot{D}_X \hat{Y} - a(\hat{Y})\hat{X} + \tilde{g}(\hat{X},\hat{Y})t - 2a(\hat{X})\hat{Y}$$

This proves the theorem.

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