

Performance of Convolutional Code Encoder Structure with Code Rate $\frac{1}{3}$ Using Particle Swarm Optimization

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Abstract: During the transmission process, the transmitted signals pass through some noisy channel. Due to noise interference, some errors are introduced in the received data. These errors can be detected and correcting using coding technique. The error correcting codes are very useful for transmitting information through noisy channels. Convolutional code is the most reliable method for transmitting or retrieving the error free data. Convolutional code encoder consists of shift registers and mod-2 adders. The performance of convolutional code depends upon the connections between shift registers and mod-2 adders. In this paper a method is proposed for convolutional code encoder structure with code rate $\frac{1}{3}$ using particle swarm optimization which is an efficient optimization technique.

Keywords: Convolutional code, PSO (particle swarm optimization), Mod-2 Adder, Shift register, coderate

1. INTRODUCTION

Today the use of digital cell phones, the internet, and CD and DVD players is ubiquitous. In all of these cases, digitally represented data is either transmitted from one place to another or retrieved from a storage device when needed. For the proper functioning of these systems the transmitted or retrieved data must be sufficiently error free. This can be accomplished efficiently by using channel efficiently coding techniques [8]. Coding techniques create code words by adding redundant information to the user information vectors. The convolutional codes takes advantage of the relativity between code blocks, so they have better error correction performance and are used widely. Unlike the block code, convolutional code is not memory-less devices.

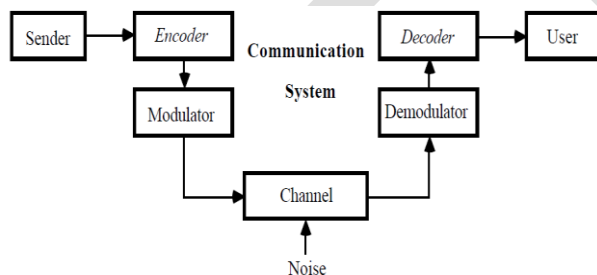


Figure 1: A simplified model of a communication system.

Because of its ability of error control, convolutional codes with longer constraint lengths are widely applied in domains such as satellite communications and digital video. Encoding algorithms generates the code word, which transmitted over the channel (Figure1). Convolutional code accepts a fixed number of message symbols and produces a fixed number of code symbols. Its computation depends not only on the current set of input symbols but also on some of previous input symbols. Convolutional code has many encoder structures (outputs connection with shift registers). The complexity of convolutional code encoder structure increased with the number of states. We have investigated that the PSO algorithm finds to be the best connections for convolutional code encoder. PSO algorithm [3] has some good features such as good diversity, wide searching area and strong global optimize capability. So the best Convolution code encoder structure with code rate $\frac{1}{3}$ based upon particles swarm optimization algorithm is presented in this paper[7]. In this paper present the best convolutional code encoder structure (connection of output with the shift registers) with code rate $\frac{1}{3}$.

2. CONVOLUTIONAL CODE

Convolutional code was introduced by Elias. A convolutional code is a type of code in which each m-bit information to be encoded is transformed into an n-bit symbol. A convolutional code introduces redundant bits into the data stream through the use of linear shift registers as shown in (Figure2). The inputs to the shift registers are information bits and the output encoded bits are obtained by modulo-2 addition of the input information bits and the contents of the shift registers. The connections to the modulo-2 adders were developed heuristically with no algebraic or combinatorial foundation.

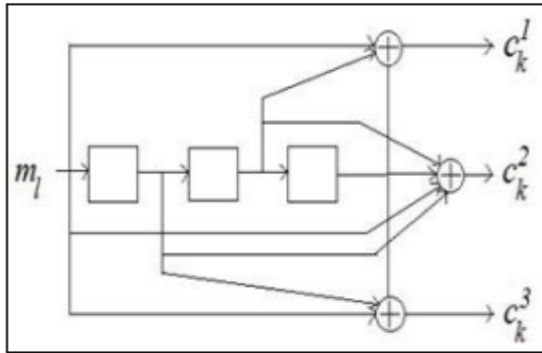


Figure 2: Convolutional encoder (Rate=1/3, K=4)

A convolutional code is described by three integers, n, k, and K. The code rate R for a convolutional code is defined as $R = k/n$, where k is the number of parallel input information bits and n is the number of parallel output encoded bits at one time interval. The constraint length K for a convolutional code is defined as $K = m + 1$, where m is the maximum number of stages (memory size) in any shift register. The number of encoder structure depends upon constraint length(K). For a particular value of K, the number of structure (N) is defined as:

$$N = (2^K - 1) * (2^K - 1)$$

3. PARTICLE SWARM OPTIMIZATION

Particle Swarm Optimization (PSO) is a technique used to explore the search space of a given problem to find the settings or parameters required to maximize a particular objective. This technique, first described by James Kennedy and Russell C. Eberhart in 1995 [6] originates from two separate concepts: the idea of swarm intelligence based off the observation of swarming habits by certain kinds of animals (such as birds and fish); and the field of evolutionary computation. The algorithm maintains a population potential where each particle represents a potential solution to an optimization problem. The PSO algorithm works by simultaneously maintaining several candidate solutions in the search space. During each iteration of the algorithm, each candidate solution is evaluated by the objective function being optimized, determining the fitness of that solution. Each candidate solution can be thought of as a particle “flying” through the fitness landscape finding the maximum or minimum of the objective function.

4. PSO ALGORITHM

The PSO algorithm consists of following steps, which are repeated until some stopping condition is met:

1. Initialize the population, location and velocity.
2. Evaluate the fitness of the individual particle (Pbest).
3. Keep track of the individual highest fitness (Gbest).
4. Modify velocity based on Pbest and Gbest location.
5. Update the particle position.
- 6.

The first three steps are fairly trivial. Fitness evaluation is conducted by supplying the candidate solution to the objective function. Individual and global best fitnesses and positions are updated by comparing the newly evaluated fitnesses against the previous individual and global best fitnesses, and replacing the best fitnesses and positions as necessary. The velocity and position update step is responsible for the optimization ability of the PSO algorithm. The velocity of each particle in the swarm is updated using the following equation:

$$v_i(t+1) = w.v_i(t) + c_1 r_1 [l_i(t) - x_i(t)] + c_2 r_2 [g(t) - x_i(t)] \text{-----(1)}$$

$$x_i(t+1) = x_i(t) + v_i(t+1) \text{-----(2)}$$

where $v_i(t)$ & $x_i(t)$ is the velocity and position of the particle at time t and parameter w , c_1 & c_2 ($0 \leq w \leq 1.2$, $0 \leq c_1 \leq 2$ and $0 \leq c_2 \leq 2$) are user supplied co-efficient. The values r_1 and r_2 ($0 \leq r_1 \leq 1$ and $0 \leq r_2 \leq 1$) are random value regenerated for each velocity update.

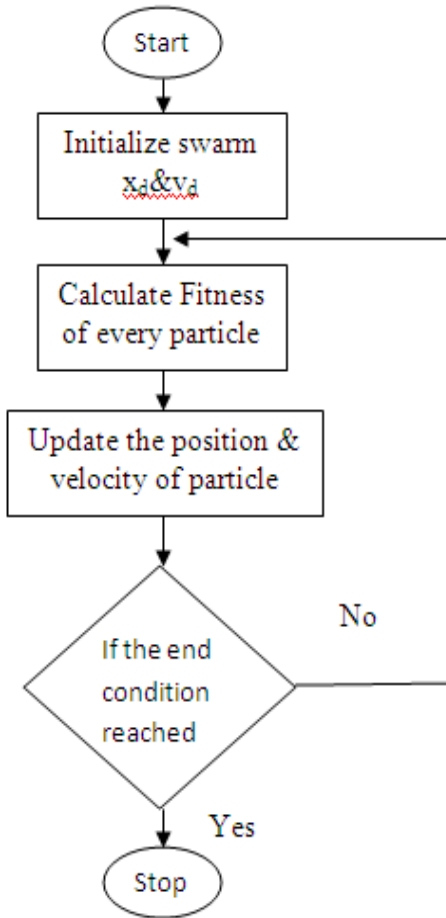


Figure 3: PSO Algorithm

5. CONVOLUTIONAL CODE OPTIMIZATION USING PSO

Optimization is the mechanism by which one finds the maximum or minimum value of a function or process. Optimization can refer to either minimization or maximization.

Step1: Generate polynomial

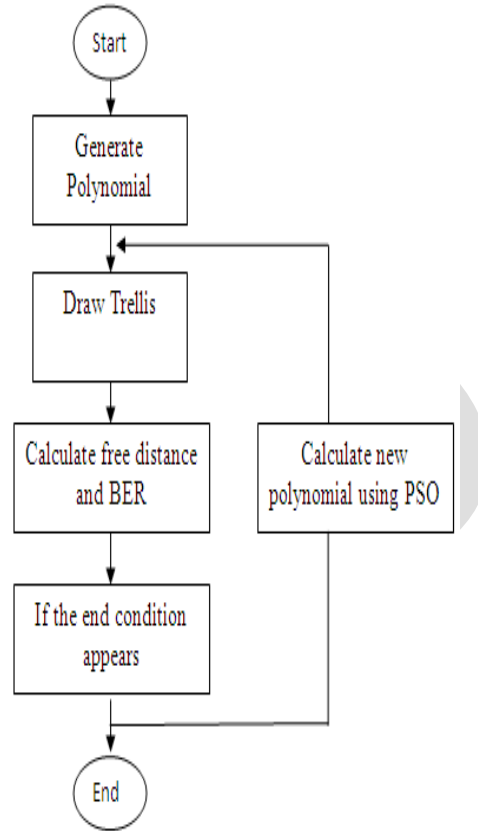
A Polynomial description of convolution encoder describes the connection among shift registers and modulo -2 adders. Build a binary number representation by placing a 1 in each connection line from shift feed into the adder and 0 elsewhere. Convert this binary representation into an octal representation.

Step2: Draw the trellis

A trellis description of a convolutional encoder shows how each possible input of encoder influences both the output and state transition of encoder. Start with a polynomial description of the encoder and use poly2trellis function to convert it to valid structure.

Step3: Calculate BER

Calculate bit error rate using octal code and trellis structure. To decode convolutional code use the vitdec function with the flag hard and with binary input data. Because the output of convenc is binary, hard decision decoding can use the output of convenc directly.



After convenc adds white Gaussian noise to the code with AWGN.

Figure 4: Convolutional Encoder using PSO

Step4 : Update particle's position and velocity

At each time, all particles have an update. At iteration t , the t^{th} element in the vector is updated. Particle's position is decided by velocity as equation (2). At the decoding process, the update of $v_i(t+1)$ and $x_i(t)$ update must act up to transfer rule of encoder state. Select lowest value of bit error rate as fitness function.

Figure 4: Convolutional Encoder using PSO

Step 5 : Update personal best position and the global best position.

Update personal best position and the global best position after all particles position have been updated.

Step 6 : Ending condition

When iteration $t=L$, all particle's position have been updated for L times and reached the grids ending

6. RESULT:

The performance of particle swarm optimization with convolutional code of code-rate 1/3 is verified using MATLAB software. The free distance d_{free} of a convolutional code is a good indicator of the error correcting performance of the code. Figure 5 represent the best connection of output with shift registers for convolutional code with code rate 1/3.

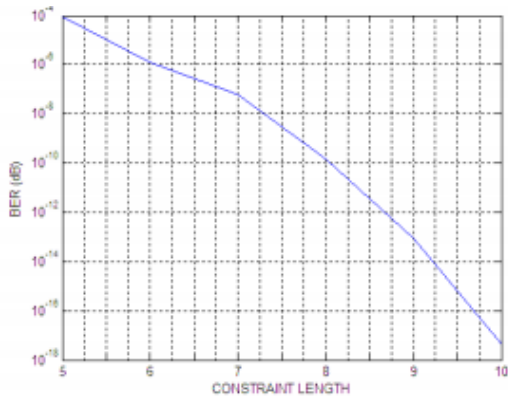


Figure 5: Graph between BER and constraint length for code rate 1/3

This is obtained with less decoding delay and also good bit error rates are achieved within less number of trials. Without optimization, to obtain such results 1000 trials or more are required.

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